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FIXED POINT RESULTS FOR JAGGI-TYPE HYBRID CONTRACTION IN JS-MODULAR METRIC SPACES

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ABSTRACT

In this paper, we introduce a new concept of JS-modular metric space and obtain some fixed-point results of hybrid contractions in this setting. Some corollaries that reduce our result to other well-known ideas in the literature are highlighted. An example is constructed to support the established concepts, and to demonstrate the distinction of this research with respect to the existing ones.

Keywords: JS-Modular Metric Space, Fixed Point, Hybrid Contraction, Jaggi-Type Contraction

INTRODUCTION

One of the well-known fixed points (FP) theorems in spaces with metric structures is the Banach Contraction (also known as the Contraction Mapping principle). It stands out due to its simplicity and wide-ranging utility in solving existence problems across various branches of mathematics and applied sciences. As a result, numerous generalizations and extensions of this principle have emerged (e.g Jiddah et al., 2022). In 2019, Karapinar & Fulga (2019) introduced a new hybrid contraction that combines Jaggi-type and interpolative-type contractions in a complete metric space (MS) setting. Jidda et al., (2022) extended the work of Karapinar & Fulga (2019) to the setting of G-MS by defining the idea of interpolative Kannan-type $(G - \alpha - \mu)$ contraction. Not long ago, in a related development, Jidda et al., (2023) studied a general class of inequalities under the name admissible $(H - \alpha - \kappa)$ contraction in a MS endowed with a graph. Yahya & Shagari (2023) defined multivalued contraction from a combination of Jaggi-type contractions, interpolative-type contraction and Pata-type inequality in the framework of MS. For further information on FP result of hybrid contraction and contractions on G-MS, the reader can consult Jidda et al., (2023).

The concept of modular spaces as a generalization of *MS* has attracted considerable interest since Nakano (1959), Musielak & Orlicz (1959) introduced the concept of modular spaces and worked on some theories about them. The idea of modular *MS* has been worked on by Chistyakov (2010), where the basic definitions and properties of modular metric are introduced. After Chistyakov (2010), many authors have studied *FP* theorems and presented significant results in modular *MS* (see for instance, [Abdou, 2013; Chaipunya *et al.*, 2012; Mongolkeha *et al.*, 2011; Mutlu *et al.*, 2018; Zhua *et al.*, 2020] and others therein).

Jleli & Samet (2015) introduced the concept of a generalized MS (now called JS-MS) and extended some well-known FP results. The concept of JS-MS recovers various concepts in topological spaces including standard MS, b-MS and modular spaces. Turkoglu & Manav (2018) considering both a modular MS and a JS-MS later introduced a new concept of JS-modular MS and proved some FP results in this setting. Interestingly, Manav (2021), using Nadler (1969) and Edelstein's result in the work of Abdou (2013), proved Caristi and Feng-Liu type FP theorems for multivalued contractive-type map in generalised modular MS. Later on, Manav & Agarwal (2023) studied best approximation of FP results for Branciari Contraction of integral type on generalized modular MS. For some recent results, see e.g, Okeke & Francis (2024).

Following the reviewed literature, we see that a unified concept in the sense of Turkoglu & Manav (2018) and Karapinar & Fulga (2019) is not adequately considered. Motivated by the above information, we propose a new combinational concept under the name Jaggi-type hybrid contraction (*JHC*) in *JS*-modular *MS* and prove the existence of *FP* of such contraction. The proposed result is a direct improvement of the work of Turkoglu & Manav (2018) and Karapinar & Fulga (2019), and some related results therein. An example is constructed to support the assumptions of our established theory. Some corollaries are highlighted and discussed to show that the concept proposed therein, subsumes several existing results.

The structure of the paper is outlined as follows: Section 1 provides an introduction. In Section 2, we recall specific preliminary concepts needed in the discussion of our main results. The main result and corollaries are presented in Section 3 with an example given to support the established concepts.

Preliminaries

In this section, the basic concepts and auxiliary results needed for the presentation of our main result are collated.

Jleli & Samet (2015) defined the *JS*-MS as follows:

Definition 1

Let H be a nonempty set and $D: H \times H \to [0, +\infty]$ be a given mapping. For every $h \in H$, define the set $K(D, H, h) = \{\{h_n\} \subseteq H: \lim_{n \to \infty} \phi(h_n, h) = 0\}$

for all $\lambda > 0$. We say that *D* is a *JS*-modular metric on *H* if it satisfies

- i. for every $(h,j) \in H^2, \lambda > 0$, we have $\phi(h,j) = 0 \Rightarrow h = j$;
- ii. for every $(h,j) \in H^2, \lambda > 0$, we have $\phi(h,j) = \phi(j,h)$;
- ii. There exists K > 0 such that if $(h, j) \in H^2$, $\{h_n\} \in K(D, H, h)$ then $\phi(h, j) \le K \lim \sup \phi(h_n, j)$.

Then (H, D) is a JS-metric space.

Chistyakov (2010) gave the following definitions.

Definition 2

Let H be a vector space over \mathbb{R} (or \mathbb{C}).

- i. A functional $\rho: H \to [0, \infty]$ is called a modular if for arbitrary $h, j \in H$,
 - a. $\rho(h) = 0$ iff h = 0;
 - b. $\rho(\alpha h) = \rho(h)$ for every scalar α with $|\alpha| = 1$;

c. $\rho(\alpha h + \alpha j) \le \rho(h) + \rho(j) \text{if } \alpha + \beta = 1$ and $\alpha, \beta \ge 0$;

ii. if c) is replaced by

c')
$$\rho(\alpha h + \alpha j) \le \alpha^s \rho(h) + \beta^s \rho(j)$$
, for $\alpha, \beta \ge 0$, $\alpha^s + \beta^s = 1$ with $s \in (0,1]$,

then ρ is called an *s*-convex modular, and if $s=1, \rho$ is called a convex modular.

iii. A modular ρ defines a corresponding modular space i.e the vector subspace of H, H_{ρ} given by

$$H_{\rho} = \{ h \in H : \rho(\lambda h) \rightarrow 0 \text{ as } \lambda \rightarrow 0 \}$$

Chistyakov (2010) gave the following definition of a metric modular.

Definition 3

Let *H* be a nonempty set. A function $\varpi : (0, \infty) \times H \times H \rightarrow [0, \infty]$ is said to be a metric modular on *H* if it satisfies the following conditions:

i.
$$\varpi_{\lambda}(h,j) = 0$$
 for all $\lambda > 0$ iff $h = j$;

ii.
$$\varpi_{\lambda}(h,j) = \varpi_{\lambda}(j,h) \forall \lambda > 0;$$

iii.
$$\varpi_{\lambda+\mu}(h,j) \leq \varpi_{\lambda}(h,z) + \varpi_{\mu}(z,j), \forall \lambda, \mu > 0.$$

Jleli & Samet (2015) gave the following definition.

Definition 4

Let (H, D) be a JS-metric space. We say that

- i. $\{h_n\}$ *D*-converges to *H* if $\{h_n,\} \in K(D,H,h)$.
- ii. $\{h_n\}$ is D-Cauchy sequence if $\lim_{n\to\infty} \phi(h_n, h_{n+m}) = 0$.
- iii. (H, D) is *D*-complete if every Cauchy sequence in *H* is convergent to some element in *H*.

Definition 5((c)-comparison function)

 $\psi: [0,\infty) \to [0,\infty)$ is a (c)-comparison function if it is nondecreasing and satisfies there exists $q_0 \in \mathbb{N}$ and $r \in (0,1)$ and a convergent series $\sum_{q=1}^{\infty} w_q$ such that $w_q \ge 0$ and $\psi^{q+1} \le r \psi^q(t) + w_q$, for $q \ge q_0$ and $t \ge 0$.

The set of all (c)-comparison functions will be denoted by Ψ . Every $\psi \in \Psi$

satisfies the following:

- i. $\psi(w) \le w$, for any $w \in \mathbb{R}^+$;
- ii. ψ is continuous at 0;
- iii. the series $\sum_{q=1}^{\infty} \psi^q(w)$ is convergent for $w \ge 0$.

Karapinar & Fulga (2019) gave the following definition of Jaggi-type hybrid contraction in metric space.

Definition 6

Let (H, D) be a complete metric space. A mapping $\theta : H \to H$ is called a Jaggi-type hybrid contraction if there exists $\psi \in \Psi$ such that

$$=\begin{cases} [\sigma_1(\frac{\phi(h,\ \theta j)\phi(j,\ \theta j)}{\phi(h,\ j)})^s + \sigma_2(\phi(h,j)^s]^{\frac{1}{s}} for\ s > 0, h, j \in H, h \neq j \\ (\phi(h,\theta j))^{\sigma_1}(\phi(j,\theta j))^{\sigma_2} for\ s = 0, h, j \in H/F_{\theta}(H) \end{cases}$$

for $\sigma_i \ge 0$, i = 1,2 such that $\sigma_1 + \sigma_2 = 1$.

Karapinar & Fulga (2019) proved the following fixed-point result.

Theorem 1

A continuous self-mapping θ on (H, φ) possesses a fixed point H provided that θ is a Jaggi-type hybrid contraction. Moreover, for any $h_0 \in H$, the sequence $\{\theta^n(h_0)\}$ converges to H.

Turkoglu & Manav (2018) introduced the JS-modular metric as follows

Definition 7

Let H be a nonempty set and ϖ_{λ} : H × H \rightarrow [0,+ ∞] be a given mapping. For every h \in H, define the set

$$K(\varpi_{\lambda}, H, h) = \{\{\{h_n\}\subseteq H: \lim_{n\to\infty} \varpi_{\lambda}(h_n, h) = 0\}$$

for all $\lambda > 0$. ω_{λ} is a JS-modular metric on H if it satisfies

i. for every
$$(h, j) \in H^2, \lambda > 0$$
, we have

$$\varpi_{\lambda}(h, j) = 0 \Rightarrow h = j;$$

ii. for every $(h, j) \in H^2$, $\lambda > 0$, we have

$$\varpi_{\lambda}(h, j) = \varpi_{\lambda}(j, h);$$

iii. there exists K > 0 such that if $(h, j) \in H^2$, $\{h_n\} \in K(\varpi_{\lambda}, H, h)$, then

 $\varpi_{\lambda}(h,j) \leq K \lim \sup \varpi_{\lambda}(h_n,j).$

The pair (H, ϖ_{λ}) is called a JS-modular metric space.

RESULTS AND DISCUSSION

Definition 8

Let $(H_{\varpi}, \varpi_{\lambda})$ be a *JS*-modular metric space. A mapping $\theta: H_{\varpi} \to H_{\varpi}$ is called a hybrid contraction of Jaggi-type (HCJT) if there exists $\psi \in \Psi$ such that

$$\varpi_{\lambda}(\theta h, \theta j) \leq \psi(H_{\theta}^{s}(h, j))$$
(2)

 $\forall h, j \in H_{\varpi}$, where $s \ge 0$ and

 $H_{\theta}^{s}(h,j)$

$$=\begin{cases} [\sigma_1(\frac{\varpi_{\lambda}(h,\,\theta j)\varpi_{\lambda}(j,\,\theta j)}{\varpi_{\lambda}(h,\,j)})^s + \sigma_2(\varpi_{\lambda}(h,j))^s]^{\frac{1}{s}} for \, s > 0, \varpi_{\lambda}(h,j) \neq 0 \\ (\varpi_{\lambda}(h,\theta j))^{\sigma_1}(\varpi_{\lambda}(j,\theta j))^{\sigma_2} for \, s = 0, h, j \in H_{\varpi}/F_{\theta}(H_{\varpi}) \end{cases}$$
 for $\sigma_i \geq 0$, $i = 1,2$ such that $\sigma_1 + \sigma_2 = 1$.

Proposition 1

Suppose that θ is a HCJT. Then any fixed point $h \in H_{\varpi}$ of θ satisfying $\varpi_{\lambda}(h, h) < \infty$ implies $\varpi_{\lambda}(h, h) = 0$. Proof:

Let $h \in H_{\varpi}$ be a fixed point of θ such that $\varpi_{\lambda}(h, h) < \infty$. Since θ is a HCJT, for s > 0, if $\varpi_{\lambda}(h, h) \neq 0$, then

$$\varpi_{\lambda}(\theta h, \ \theta h) = \psi([\sigma_{1}(\frac{\varpi_{\lambda}(h,h)\varpi_{\lambda}(h,h)}{\varpi_{\lambda}(h,h)})^{s} + \sigma_{2}(\varpi_{\lambda}(h,h))^{s}]^{\frac{1}{s}})$$

- $= \psi([(\sigma_1 + \sigma_2)(\varpi_{\lambda}(h, h))^s]^{\frac{1}{s}})$
- $=\psi(\boldsymbol{\omega}_{\lambda}(h,h))$
- $< \omega_{\lambda}(h,h)$

Hence, we have $\varpi_{\lambda}(h,h) = \varpi_{\lambda}(\theta h, \theta h) < \varpi_{\lambda}(h,h)$. This is a contradiction.

Hence, $\varpi_{\lambda}(h, h) = 0$. Similarly, for s = 0, if $\varpi_{\lambda}(h, h) \neq 0$, then

 $\varpi_{\lambda}(h,h) = \varpi_{\lambda}(\theta h, \theta h)$

 $\leq \psi((\varpi_{\lambda}(h,\theta h))^{\sigma_1}(\varpi_{\lambda}(h,\theta h))^{\sigma_2})L$

 $<(\varpi_{\lambda}(h,\theta h))^{\sigma_1}(\varpi_{\lambda}(h,\theta h))^{\sigma_2}$

- $= (\varpi_{\lambda}(h,\theta h))^{\sigma_1 + \sigma_2}$
- $= \varpi_{\lambda}(h, \theta h)$
- $= \omega_{\lambda}(h,h)$

This is a contradiction. Hence $\varpi_{\lambda}(h, h) = 0$.

Proposition 2

Let $(H_{\varpi}, \varpi_{\lambda})$ be a JS-modular metric. Let $\{h_n\}$ be a sequence in H_{ϖ} and $(h, j) \in H_{\varpi} \times H_{\varpi}$ such that $\varpi_{\lambda}(h_n, h) \to 0$, $\varpi_{\lambda}(h_n, j) \to 0$ as $n \to \infty$ for some $\lambda > 0$. Then h = j. Proof:

Using the property iii), we have

$$\varpi_{\lambda}(h,j) \leq K \lim \sup \varpi_{\lambda}(h_n,j) = 0.$$

$$n \rightarrow \infty$$

which implies from the property i) that h = j. \Box

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Theorem 2
Suppose that the following conditions holds:
      i. (H_{\varpi}, \varpi_{\lambda}) is a JS-modular metric space.
     ii. \theta is a continuous HCJT.
    iii. there exists h_0 \in H_{\overline{\omega}} such that
\delta(\varpi_{\lambda}, \theta, h_0) = \sup \{ \varpi_{\lambda}(\theta^i(h), \theta^l(h)) \} < \infty.
 Then the sequence \{\theta^n(h_0)\}\ \varpi_{\lambda}-converges to h \in H_{\varpi}, a unique fixed point of \theta.
Proof: Let n \in \mathbb{N} and h_0 \in H_{\varpi}. Since \theta is a HCJT, \forall i, l \in \mathbb{N} \cup \{0\}, we have
\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+l}(h_0)) \leq \psi(H_{\theta}^{s}(\theta^{n-1+i}(h_0), \theta^{n-1+l}(h_0)))
We shall prove the claim of the theorem by examining the two cases: s > 0 and s = 0.
for s > 0 and taking l = i + 1, the expression (2) becomes
\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0)) \le \psi(H_{\theta}^s(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0)))
                                                                                                                                               (4)
H^{s}_{\theta}\left(\theta^{n-1+i}(h_{0}),\theta^{n+i}(h_{0})\right) = \left[\sigma_{1}\left(\frac{\varpi_{\lambda}(\theta^{n-1+i}(h_{0}),\theta^{n+i}(h_{0}))\varpi_{\lambda}(\theta^{n+i}(h_{0}),\theta^{n+i+i}(h_{0}))}{\varpi_{\lambda}(\theta^{n-1+i}(h_{0}),\theta^{n+i}(h_{0}))}\right)^{s} + \sigma_{2}\left(\varpi_{\lambda}(\theta^{n-1+i}(h_{0}),\theta^{n+i}(h_{0}))\right)^{s}\right]^{\frac{1}{s}}
Therefore (3) becomes
\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0)) \leq \psi[\sigma_1(\varpi_{\lambda}(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0)))^s + \sigma_2(\varpi_{\lambda}(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0)))^s]^{\frac{1}{s}}
Now suppose that
\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+i+1}(h_0)) \ge \varpi_{\lambda}(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0))
\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+i+1}(h_0)) \leq \psi[\sigma_1(\varpi_{\lambda}(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0)))^s + \sigma_2(\varpi_{\lambda}(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0)))^s]^{\frac{1}{s}}
= \psi[\sigma_1(\varpi_{\lambda}(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0)))^s + \sigma_2(\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+i+1}(h_0)))^s]^{\frac{1}{s}}
= \psi([(\sigma_1 + \sigma_2)(\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+i+1}(h_0)))^s]^{\frac{1}{s}}
=\psi(\varpi_{\lambda}(\theta^{n+i}(h_0),\theta^{n+i+1}(h_0)))
=\varpi_{\lambda}(\theta^{n+i}(h_0),\theta^{n+i+1}(h_0))
This is a contradiction, hence we obtain that
\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+i+1}(h_0)) \leq \varpi_{\lambda}(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0))
Since \delta(\varpi_{\lambda}, \theta, h) = \sup{\{\varpi_{\lambda}(\theta^{i}(h), \theta^{l}(h))\}}, The expression (4) becomes
\delta(\varpi_{\lambda},\theta,\theta^n(h_0)) \leq \psi(\delta(\varpi_{\lambda},\theta,\theta^{n-1}(h_0)))
\leq \psi^2(\delta(\varpi_{\lambda},\theta,\theta^{n-2}(h_0)))
\leq \psi^n(\delta(\varpi_{\lambda}, \theta, h_0).
Let n, m \in \mathbb{N} with m > n. By using the property of the (c)-comparison function,
\delta(\theta^n(h_0), \theta^{n+m}(h_0)) \le \delta(\varpi_{\lambda}, \theta, \theta^n(h_0))
\leq \psi^n(\delta(\varpi_\lambda, \theta, h_0) \to 0 \text{ as } n \to \infty.
This implies that \{\theta^n(h_0)\}\ is an \varpi_{\lambda}-Cauchy sequence. Since (H_{\varpi}, \varpi_{\lambda}) is \varpi_{\lambda}-complete, there exists h \in H_{\varpi} such that \{\theta^n(h_0)\}
is \varpi_{\lambda}-convergent to H. Now, since \theta is continuous, it follows from Proposition 3 that

\varpi_{\lambda}(h,\theta j) = \lim_{n \to \infty} (\theta^n(h_0), \theta(\theta^n(h_0)))

= \lim \left( \theta^n(h_0), \theta^{n+1}(h_0) \right)
= \varpi_{\lambda}(h_0, h_0)
= 0,
which shows that H is a fixed point of \theta.
To show uniqueness, suppose that \{\theta^n(h_0)\}\ is \varpi_{\lambda}-convergent to j, then by
Proposition 3.2, we have that h = j.
for s > 0 and taking l = i + 1, the expression (2) becomes

\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0)) \le \psi(H_{\theta}^s(\theta^{n-1+i}(h_0), \theta^{n+i}(h_0)))

= \psi((\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0)))^{\sigma_1}(\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0)))^{\sigma_2})
  <(\varpi_{\lambda}(\theta^{n+i}(h_0),\theta^{n+1+i}(h_0)))^{\sigma_1}(\varpi_{\lambda}(\theta^{n+i}(h_0),\theta^{n+1+i}(h_0)))^{\sigma_2}
The above inequality turns into
(\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0)))^{1-\sigma_1} < (\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0)))^{\sigma_2}
and since \sigma_1 + \sigma_2 = 1, we have
\varpi_{\lambda}\left(\theta^{n+i}(h_0),\theta^{n+1+i}(h_0)\right) < (\varpi_{\lambda}(\theta^{n+i}(h_0),\theta^{n+1+i}(h_0))
Returning to (5), we find that,
\varpi_{\lambda}\left(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0)\right) < (\varpi_{\lambda}(\theta^{n+i}(h_0), \theta^{n+1+i}(h_0))
                                                                                                                             (6)
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Since $\delta(\varpi_{\lambda}, \theta, h) = \sup{\{\varpi_{\lambda}(\theta^{i}(h), \theta^{l}(h))\}}$, The expression (6) becomes

 $\delta(\varpi_{\lambda}, \theta, \theta^{n}(h_{0})) \leq \psi(\delta(\varpi_{\lambda}, \theta, \theta^{n-1}(h_{0})))$

 $\leq \psi^2(\delta(\varpi_{\lambda}, \theta, \theta^{n-2}(h_0)))$

 $\leq \psi^n(\delta(\varpi_{\lambda}, \theta, h_0).$

By using the same tools as in the case of s > 0, we find that $\{\theta^n(h_0)\}$ is an ϖ_{λ} -Cauchy sequence in a ϖ_{λ} -complete *JS*-modular metric space. Hence, there exists $h \in H_{\varpi}$ such that $\{\theta^n(h_0)\}$ is ϖ_{λ} -convergent to *H*. It follows that *H* is a unique fixed point of θ .

In the following result, we establish the existence of fixed point of θ under the restriction of containity of some iterate of θ .

Theorem 3

Let $(H_{\varpi}, \varpi_{\lambda})$ be a complete JS-modular metric space and $\theta: H_{\varpi} \to H_{\varpi}$ be a HCJT. If for some $i \geq 1$, θ^i is continuous, then θ has a fixed point in H_{ϖ} .

Proof:

In Theorem 3.3, we have established that there exists an ϖ_{λ} - Cauchy sequence $\{h_n\}$ in $(H_{\varpi}, \varpi_{\lambda})$ with $h_n = \theta h_{n-1}$ such that $h_n \to h$ for some $h \in H_{\varpi}$. Let $\{h_{n_k}\}$ be a subsequence of $\{h_n\}$ where $n_k = k.i$ for some $k \in \mathbb{N}$, k > 1 fixed. Notice that θ^0 is an identity self-mapping on H_{ϖ} so that $h_{n_k} = \theta^i x_{n_k-1}$. Hence, by continuity of θ^i , we have

$$\varpi_{\lambda}(h,\theta^{i}h) = \lim_{k \to \infty} \varpi_{\lambda}(h,\theta^{i}h_{n_{k}-i})$$

$$=\lim_{k\to\infty} \varpi_{\lambda}(h,h_{n_k})$$

$$= \varpi_{\lambda}(h,h)$$

$$= 0,$$

which means that H is a fixed point of θ^i . Now, to see that H is a fixed point of θ , assume by contradiction that $\theta h \neq h$. Then in that case $\theta^{i-m-1}h \neq \theta^{i-m}$ for any m = 0, 1, ..., i-1. Again, we must consider two cases. Case (1): for s > 0, by replacing h by $\theta^{i-m-1}h$ and j by $\theta^{i-m}h$, we have

$$H_{\theta}^{s}(\theta^{i-m-1}h,\theta^{i-m}h) = \left[\sigma_{1}\left(\frac{\varpi_{\lambda}(\theta^{i-m-1}h,\theta(\theta^{i-m-1}h)\varpi_{\lambda}(\theta^{i-m-1}h,\theta(\theta^{i-m}h))}{\varpi_{\lambda}(\theta^{i-m-1}h,\theta^{i-m}h)}\right)^{s} + \sigma_{2}\left(\varpi_{\lambda}(\theta^{i-m-1}h,\theta^{i-m}h)\right)^{s}\right]^{\frac{1}{s}}$$

and since θ is a *HCJT*,

$$\varpi_{\lambda}(\theta^{i-m}h, \theta^{i-m+1}h) = \varpi_{\lambda}(\theta(\theta^{i-m-1}h), \theta(\theta^{i-m}h))$$

$$\leq \psi(H_{\theta}^{s}(\theta^{i-m-1}h,\theta^{i-m}h))$$

$$= \psi([\sigma_1(\varpi_\lambda(\theta^{i-m-1}h,\theta(\theta^{i-m-1}h)))^s)$$

$$+\sigma_2\left(\varpi_{\lambda}\left(\theta^{i-m-1}h,\theta^{i-m}h\right)\right)^s\right]^{\frac{1}{s}}$$

$$< [\sigma_1(\varpi_\lambda(\theta^{i-m-1}h,\theta(\theta^{i-m-1}h)))^s + \sigma_2(\varpi_\lambda(\theta^{i-m-1}h,\theta^{i-m}h))^s]^{\frac{1}{s}}$$

which yields that

$$\left(\varpi_{\lambda}(\theta^{i-m}h,\theta^{i-m+1}h)\right)^{s}(1-\sigma_{1}) < \sigma_{2}(\varpi_{\lambda}(\theta^{i-m-1}h,\theta^{i-m}h))^{s}$$

However, $\sigma_1 + \sigma_2 = 1$, so that for every m = 0, 1, ..., i - 1,

$$\varpi_{\lambda}(\theta^{i-m}h, \theta^{i-m+1}h) < \varpi_{\lambda}(\theta^{i-m-1}h, \theta^{i-m}h).$$

This clearly implies that for every k = m, m + 1, ..., i - 1,

$$\varpi_{\lambda}(\theta^{i-m}h, \theta^{i-m+1}h) < \varpi_{\lambda}(\theta^{i-m-k-1}h, \theta^{i-m-k}h).$$

Taking in particular m = 0 and k = i - 1 in the above inequality, we get

$$\varpi_{\lambda}(h, \theta^{i}h) < \varpi_{\lambda}(\theta^{i}h, \theta^{i+1}h) < \varpi_{\lambda}(h, \theta h)$$

which is a contradiction. Consequently, $\theta h = h$.

To show uniqueness, suppose that $\{\theta^n(h_0)\}\$ is ϖ_{λ} -convergent to h, then by Proposition 3.2, we have that the fixed point is unique.

Case (2):

for s = 0, by replacing h by $\theta^{i-m-1}h$ and j by $\theta^{i-m}h$, we have

$$H^{s}_{\theta}(\theta^{i-m-1}h,\theta^{i-m}h) = [\varpi_{\lambda}(\theta^{i-m-1}h,\theta(\theta^{i-m-1}h))]^{\sigma_{1}}[\varpi_{\lambda}(\theta^{i-m}h,\theta(\theta^{i-m}h))]^{\sigma_{2}}$$

$$= \left[\varpi_{\lambda}(\theta^{i-m-1}h, \theta^{i-m}h) \right]^{\sigma_1} \left[\varpi_{\lambda}(\theta^{i-m}h, \theta^{i-m+1}) \right]^{\sigma_2}$$

and the inequality becomes

$$\varpi_{\lambda}(\theta^{i-m}h,\theta^{i-m+1}h) = \varpi_{\lambda}(\theta(\theta^{i-m-1}h),\theta(\theta^{i-m}h)) \leq \psi(H_{\theta}^{s}(\theta^{i-m-1}h,\theta^{i-m}h))$$

$$= \psi([\varpi_{\lambda}(\theta^{i-m-1}h, \theta^{i-m}h)]^{\sigma_1}[\varpi_{\lambda}(\theta^{i-m}h, \theta^{i-m+1})]^{\sigma_2})$$

$$<[\varpi_{\lambda}(\theta^{i-m-1}h,\theta^{i-m}h)]^{\sigma_1}[\varpi_{\lambda}(\theta^{i-m}h,\theta^{i-m+1})]^{\sigma_2}$$

By simple calculation, we get

$$\varpi_{\lambda}(\theta^{i-m}h,\theta^{i-m+1}h) < \varpi_{\lambda}(\theta^{i-m-1}h,\theta^{i-m}h),$$

and using the same tools as in the Case (1) and Proposition 3.2, we obtain

that H is a unique fixed point of θ .

Corollary 1

Let $(H_{\varpi}, \varpi_{\lambda})$ be a complete JS-modular metric space. Suppose that the continuous mapping $\theta: H_{\varpi} \to H_{\varpi}$ satisfies $\varpi_{\lambda}(\theta h, \theta j) \leq \psi(\varpi_{\lambda}(h, j))$

 $\forall h, j \in H_{\varpi}$. Then θ has a fixed point in H_{ϖ} .

Proof

Letting $\sigma_1 = 0$, $\sigma_2 = 1$ and s > 0, the result follows. \Box

Corollary 2

(see Turkoglu & Manav (2018), Theorem 3.1) Let $(H_{\varpi}, \varpi_{\lambda})$ be a complete JS-modular metric space. Let θ : $H_{\varpi} \rightarrow H_{\varpi}$ be an ϖ_{λ} -contraction mapping, i.e

 $\forall h,j\in H_{\varpi},\,k\in(0,1).$ $\varpi_{\lambda}(\theta h, \theta j) \leq k \varpi_{\lambda}(h, j)$

Then, θ has a unique fixed point (say u) and θ is continuous at

Proof

Consider Definition 3.1 and let $\psi(t) = kt$, $\sigma_1 = 0$, $\sigma_2 = 1$ and s = 01, we have

 $\varpi_{\lambda}(\theta h, \theta j) \leq k(H_{\theta}^{s}(h, j)) = k\varpi_{\lambda}(h, j),$

which coincides with Theorem 3.1 due to Turkoglu & Manav (2018) and so the proof follows. \Box

Example 1

Let
$$H_{\varpi} = [0, \infty)$$
, $\sigma: H_{\varpi}^2 \to \mathbb{R}_+$ and define $\varpi_{\lambda}: (0, \infty) \times H_{\varpi} \times H_{\varpi} \to [0, +\infty]$ by $\varpi_{\lambda}(h, j) = \frac{\max{\{|h|, |j|\}}}{\lambda} \ \forall h, j \in H_{\varpi}.$
Then, $(H_{\varpi}, \varpi_{\lambda})$ is a complete JS-modular

$$\varpi_{\lambda}(h,j) = \frac{\max\{|h|,|j|\}}{\lambda} \, \forall h,j \in H_{\varpi}$$

metric space. Consider the mapping θ : $H_{\varpi} \rightarrow$ H_{ω} defined by

$$\Theta h = \begin{cases} \frac{1}{12}h, & h \in [0,1] \\ 1, & h = 1 \end{cases}$$

Define the function $\psi \colon \mathbb{R}_+ \to \mathbb{R}_+$. It is clear that ψ is a (c)comparison function. Let $\sigma_1 = 0$, $\sigma_2 = 1$. For s > 0, if $h, j \in [0,1]$ with h > j, then,

with
$$h > j$$
, then,
$$\varpi_{\lambda}(\theta h, \theta j) = \frac{\max\{|\theta h|, |\theta j|\}}{\lambda} = \frac{1}{12\lambda} h$$

$$\psi(H_{\theta}^{s}(h, j)) = \frac{5}{6} \varpi_{\lambda}(h, j) = \frac{5}{6} \frac{\max\{|h|, |j|\}}{\lambda} = \frac{5}{6\lambda} h$$
Hence, $\varpi_{\lambda}(\theta h, \theta j) \leq \psi(H_{\theta}^{s}(h, j))$.

if
$$h, j \in (1, \infty)$$
, $\varpi_{\lambda}(\theta h, \theta j) = \frac{1}{12\lambda} < \frac{5}{6\lambda} h \le \psi(H_{\theta}^{s}(h, j))$

If
$$h \in [0,1]$$
 and $j > 1$, then,

$$\varpi_{\lambda}(\theta h, \theta j) = \frac{\max\{|\theta h|, |\theta j|\}}{\lambda} = \frac{1}{12\lambda}$$

If
$$h \in [0, 1]$$
 and $j > 1$, then,
$$\varpi_{\lambda}(\theta h, \theta j) = \frac{\max\{|\theta h|, |\theta j|\}}{\lambda} = \frac{1}{12\lambda}$$

$$\psi(H_{\theta}^{s}(h, j)) = \frac{5}{6} \varpi_{\lambda}(h, j) = \frac{5}{6} \frac{\max\{|h|, |j|\}}{\lambda} = \frac{5}{6\lambda}j$$
Hence, $\varpi_{\lambda}(\theta h, \theta j) \leq \psi(H_{\theta}^{s}(h, j))$.

For
$$s = 0$$
, $\psi(H_{\theta}^{s}(h, j)) = \frac{5}{6} \varpi_{\lambda}(j, \theta j)$.

If
$$h, j \in [0, 1]$$
 with $h < j$, then

$$\varpi_{\lambda}(\theta h, \theta j) = \frac{\max\{|\theta h|, |\theta j|\}}{\lambda} = \frac{1}{121}$$

If
$$h, j \in [0, 1]$$
 with $h < j$, then
$$\varpi_{\lambda}(\theta h, \theta j) = \frac{\max\{|\theta h|, |\theta j|\}}{\lambda} = \frac{1}{12\lambda}j$$

$$\psi(H_{\theta}^{s}(h, j)) = \frac{5}{6}\varpi_{\lambda}(j, \theta j) = \frac{5}{6}\frac{\max\{|j|, |\theta j|\}}{\lambda} = \frac{5}{6\lambda}j$$
Hence, $\varpi_{\lambda}(\theta h, \theta j) \le \psi(H_{\theta}^{s}(h, j))$.

For $h, j \in (1, \infty)$,

$$\varpi_{\lambda}(\theta h, \theta j) = \frac{\max{\{\frac{1}{12^{j}12}\}}}{\lambda} = \frac{1}{12\lambda}$$

$$\psi(H_{\theta}^{S}(h, j)) = \frac{5}{6} \varpi_{\lambda}(j, \theta j) = \frac{5}{6} \frac{\max{\{|j|, |\theta j|\}}}{\lambda} = \frac{5}{6\lambda}j$$
Hence, $\varpi_{\lambda}(\theta h, \theta j) \leq \psi(H_{\theta}^{S}(h, j))$.

If
$$h \in [0,1]$$
 and $j > 1$,

$$\varpi_{\lambda}(\theta h, \theta j) = \frac{\max_{\{12'12'\}}}{\lambda} = \frac{1}{12\lambda}$$

$$\begin{aligned} & \text{Tr} \ h \in [0,1] \ \text{and} \ j > 1, \\ & \text{Tr} \ \lambda(\theta h, \theta j) = \frac{\max{\{\frac{1}{12'12'}\}}}{\lambda} = \frac{1}{12\lambda} \\ & \psi(H_{\theta}^{s}(h,j)) = \frac{5}{6} \varpi_{\lambda}(j, \theta j) = \frac{5}{6} \frac{\max{\{|j|, |\theta j|\}}}{\lambda} = \frac{5}{6\lambda}j \\ & \text{Hence, } \varpi_{\lambda}(\theta h, \theta j) \leq \psi(H_{\theta}^{s}(h,j)). \end{aligned}$$

Therefore, all the assumptions of Theorem 3.3 are satisfied. Consequently, θ has a unique fixed point given by h = 0.

Remark

From Example 3.1 above, ϖ_{λ} is not a modular metric since h = j $\rightarrow \varpi_{\lambda}(h,j) = 0$. Also, Karapinar & Fulga (2019) declared (Definition 2.6) that H and j are distinct, since $J_{\theta}^{s}(h, j)$ is undefined for Case (1) if h = j. However, $h = j \nrightarrow \varpi_{\lambda}(h,j) = 0$ in our definition. Therefore, our HCJT is not Jaggi-type contraction defined by Karapinar & Fulga (2019), and so

Theorem 2.1 due to Karapinar & Fulga (2019) is not applicable to this example.

CONCLUSION

This study presented a general idea of a contraction named Jaggi-type hybrid contraction in a JS-modular MS. In Theorem 3.3, sufficient conditions under which such contraction posses a unique FP have been presented. We also established the FP existence of the map θ when continuity is restricted only to some iterate of θ in Theorem 3.4. Corollaries 3.5 and 3.6 are provided to show that the approach described herein is a generalization and improvement on some related results in the literature. Example 3.1 has been constructed to support the assumptions of our obtained result and show the relationship between the ideas of this paper and the corresponding literature.

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