

APPLICATION OF NON-STANDARD FINITE DIFFERENCE METHOD ON COVID-19 MATHEMATICAL MODEL WITH FEAR OF INFECTION

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ABSTRACT

This study presents a novel application of Non -Standard Finite Difference (NSFD) Method to solve a COVID-19 epidemic mathematical model with the impact of fear due to infection. The mathematical model is governed by a system of first-order non-linear ordinary differential equations and is shown to possess a unique positive solution that is bounded. The proposed numerical scheme is used to obtain an approximate solution for the COVID-19 model. Graphical results were displayed to show that the solution obtained by NSFD agrees well with those obtained by the Runge-Kutta-Fehlberg method built-in Maple 18.

Keywords: Differential Equations, COVID-19 Mathematical Model, Non-Standard Finite Difference, Approximate Solution

INTRODUCTION

The use of differential equations to model the transmission dynamics of infectious disease can be traced back to 1970 when Daniel Bernoulli justified the use of inoculation to curb the spread of smallpox (Dietz and Heesterbeek, 2002; Foppa, 2017). These models are usually nonlinear (Peter et al., 2020; Gu et al., 2023; Akinyemi et al., 2023; Kambali et al., 2023; Ochi et al., 2023) and are difficult to obtain their exact solution (Onwubuoya et al., 2018b; Riyapan et al., 2021; ur Rehman et al., 2023).

Thus, numerical methods are used to obtain approximate solutions. Some of the numerical techniques are Euler (Ashigi et al., 2021; Mohammed et al., 2021; Reza et al., 2022), Euler Predictor Corrector (Onwubuoya et al., 2018a), Non-Standard Finite Difference (Raza et al., 2022; Butt et al., 2023; ur Rehman et al., 2023).

The Non-Standard Finite Difference (NSFD) method developed by Ronald E. Mickens is a discrete representation of a continuous model (Mickens and Washington, 2012, Qui et al., 2014). Apart from predicting the behaviour of the dynamical system correctly, the NSFD method is known to preserve the dynamical properties of an epidemic model and is less difficult to implement when compared with the aforementioned numerical methods (Qui et al., 2014). Applications of NSFD method are found in financial theory (Mehdizadeh et al., 2022; Mehdizadeh et al., 2023), epidemiology (ur Rehman et al., 2023, Butt et al., 2023), enzymology (Miller & O'Riordan, 2020; Zafar et al., 2023), pharmacology (Egbelowo, 2018; Egbelowo & Hoang, 2021), immunology (Costa et al., 2023; Elaiw et al., 2023).

The purpose of this study is to apply the NSFD scheme to solve a mathematical model presented in Ibrahim (2023). The mathematical model proposed by Ibrahim (2023), describes

the spread of COVID-19 in the presence of fear of infection and is governed by the following system of nonlinear differential equations.

$$\left. \begin{aligned} \frac{dS}{dt} &= P - \Omega S - K_1 S + v_2 V \\ \frac{dV}{dt} &= v_1 S - e \Omega V - K_2 V \\ \frac{dE}{dt} &= \Omega(S + eV) - K_3 E \\ \frac{dQ}{dt} &= \tau_1 E - K_4 Q \\ \frac{dA}{dt} &= \theta_1 E - K_5 A \\ \frac{dI}{dt} &= \theta_2 A - K_6 I \\ \frac{dH}{dt} &= \theta_3 Q + \tau_2 I - K_7 H \\ \frac{dR}{dt} &= \alpha_1 A + \alpha_2 I + \alpha_3 H - \mu R \\ \frac{dD}{dt} &= l_1 A + l_2 I + l_3 H - \phi D \\ \frac{dW}{dt} &= \Pi I + \Pi \theta H - \varepsilon W \end{aligned} \right\} \quad (1)$$

Subject to $S(0) = 1.885103470 \times 10^8$, $V(0) = 2.672 \times 10^7$, $E(0) = 3,500$, $Q(0) = 400$, $A(0) = 1,247$, $I(0) = 800$, $H(0) = 652$, $R(0) = 249,911$, $D(0) = 3143$ and $W(0) = 1000$.

$$\Omega = \frac{\beta(A\eta_1 + H\eta_2 + W\eta_3 + I)}{\chi_1 D + 1}, \quad K_1 = \mu + v_1, \quad K_2 = \mu + v_2, \quad K_3 = \mu + \theta_1 + \tau_1, \quad K_4 = \mu + \theta_3, \quad K_5 = \mu + \theta_2 + \alpha_1 + \delta_1, \quad K_6 = \mu + \tau_2 + \alpha_2 + \delta_2, \quad K_7 = \mu + \alpha_3 + \delta_3, \quad l_1 = \mu + \delta_1, \quad l_2 = \mu + \delta_2, \quad l_3 = \mu + \delta_3 \text{ and } e = 1 - b.$$

Table 1: Description of State Variables of the Model

State Variable	Meaning
$S(t)$	Unvaccinated Susceptible Individuals
$V(t)$	Vaccinated Susceptible Individuals
$E(t)$	Exposed Individuals
$Q(t)$	Quarantined Individuals

$A(t)$	Asymptomatic Individuals
$I(t)$	Symptomatic Individuals
$H(t)$	Hospitalized Individuals
$R(t)$	Recovered Individuals
$D(t)$	COVID-19 Dead Individuals
$W(t)$	Concentration of COVID-19 Viruses in the Environment

Table 2: Description of Parameters for the Model

Parameters	Description of Parameters	Hypothetical Values	Source
N_0	Total Population of Active Humans	215,497,404	Worldometer, 2022
P	Recruitment rate.	μN_0	Estimated
μ_0	Estimated average life span of Nigerian	55.75 per year	Worldometer, 2022
μ	Natural death rate.	$\frac{1}{\mu_0 \times 365}$ per day	Estimated
$\delta_1, \delta_2, \delta_3$	COVID-19 induced death rate for individuals in A, I and H compartments respectively.	0.018, 0.025, 0.01	Estimated Nana-Kyere et al., 2022
$\alpha_1, \alpha_2, \alpha_3$	The recovery rate for individuals in A, I and H compartments respectively.	0.0195692, 0.004165, 0.0701	Diagne et al., 2021
b	Rate of COVID-19 efficacy	0.6309	WHO, 2021
v_1	Vaccination rate for susceptible individuals		Diagne et al., 2021
v_2	Waning rate of COVID-19 vaccine	0.4, 0.095	Paul and Kuddus, 2022
τ_1	Quarantine rate for exposed individuals	0.012	Nana-Kyere et al., 2022
θ_1, θ_2	Progression rate for individuals in E to A and A to I compartments respectively	0.7, 0.08	Srivastav et al., 2021
θ_3, τ_2	The hospitalization rate for individuals in Q and I compartments respectively.	0.06, 0.02	Nana-Kyere et al., 2022
η_1, η_2, η_3	Modification parameters associated with reduction of infectiousness for individuals in A, H and W as compared to I class respectively.	0.75, 0.5, 0.33	Garba et al., 2020
π	Shedding rate of coronavirus into the environment.	0.002	Garba et al., 2020
ϑ	Modification parameters associated with reduction of shedding for individuals in H as compared to I class respectively.	0.5	Garba et al., 2020
ε	The decay rate of coronavirus in the environment.	0.85	Garba et al., 2020
ϕ	Burial rate of dead infectious individuals.		Aba Oud et al., 2021
χ_1	Level of fear associated with COVID-19 infection.	0.2276 (0,1)	Estimated
β	COVID-19 transmission coefficient	$\frac{\beta_0}{N_0}$ $\beta_0 = 0.1086$	Estimated Adewole et al., 2021

The rest of this paper is arranged as follows: Section 2 presents the material and methods. Results and discussion are addressed in Section 3. Section 4 gives the conclusion of the study.

MATERIALS AND METHODS

This section deals with the introduction to NSFD, the dynamical properties of Model (1) and the application of NSFD on Model (1).

Basic Concept of NSFD

First, we consider an autonomous ordinary differential equation of the form

$$\frac{dx}{dt} = f(x(t)) \quad (2)$$

Definition 1: A discretized form of (2) is called an NSFD scheme provided at least one of these conditions is satisfied.

1. The discretized representation of (2) is

$$\frac{dx}{dt} \rightarrow \frac{x_{n+1} - G(h)x_n}{Z(h)} \quad n = 0, 1, \dots, M-1 \quad (3)$$

such that $t_n = t_0 + hn$, $x_n = x(t_n)$, $h = \frac{T}{M}$ the numerator function $G(h) = 1 + O(h)$, and the denominator function $Z(h) = h + O(h^2)$.

2. The nonlinear term $f(x)$ in (2) should be approximated using the nonlocal discretized form. For instance,

$$x^2 \approx x_n x_{n+1} \quad (4)$$

Here, T is the final time, h the time step size and M the number of iterations. Again, we consider a system of first-order nonlinear differential equations

$$\left. \begin{aligned} \frac{dx_1}{dt} &= -a_1 x_1 x_2 - b_1 x_1 \\ \frac{dx_2}{dt} &= a_1 x_1 x_2 + b_2 x_2 \end{aligned} \right\} \quad (5)$$

subject to $x_1(0) = c_1$ and $x_2(0) = c_2$.

Discretized (5) using the semi-implicit finite scheme while ensuring that the above condition conditions are met to have

$$\left. \begin{aligned} \frac{x_{1,n+1} - G_1 x_{1,n}}{Z_1} &= -a_1 x_{1,n+1} x_{2,n} - b_1 x_{1,n+1} \\ \frac{x_{2,n+1} - G_2 x_{2,n}}{Z_2} &= a_1 x_{1,n+1} x_{2,n} - b_2 x_{2,n+1} \end{aligned} \right\} \quad (6)$$

$$n = 0, 1, \dots, M$$

Following Ahmed (2011) and Sweilam et al. (2017), to have $G_1 = G_2 = 1$ and an exponential denominator function $Z_1 = \frac{e^{b_1 h} - 1}{b_1}$ and $Z_2 = \frac{e^{b_2 h} - 1}{b_2}$, are used. Hence, (6) becomes

$$\left. \begin{aligned} x_{1,n+1} &= \frac{x_{1,n}}{Z_1(a_1 x_{2,n} + b_1) + 1} \\ x_{2,n+1} &= \frac{x_{2,n}(a_1 x_{1,n+1} Z_2 + 1)}{Z_2 b_2 + 1} \end{aligned} \right\} \quad (7)$$

Remark [Sweilam et al. (2017)]: Whenever the denominator function $Z(h) = h$, the scheme is called NSFD-I, otherwise it is called NSFD-II.

Thus, this study utilizes the NSFD-II scheme. Next, the dynamical properties such as the existence and uniqueness, positivity and boundedness solution of Model (1) are examined.

Existence and Uniqueness Solution of the Covid-19 Model

Theorem 2.1: The system (1) has a unique solution in the region $(S, V, E, Q, A, I, H, R, D, W) \in \mathbb{R}_+^{10}$

Proof: We write the right-hand side of Model (1) as

$$\left. \begin{aligned} f_1 &= P - \Omega S - K_1 S + v_2 V \\ f_2 &= v_1 S - e\Omega V - K_2 V \\ f_3 &= \Omega(S + eV) - K_3 E \\ f_4 &= \tau_1 E - K_4 Q \\ f_5 &= \theta_1 E - K_5 A \\ f_6 &= \theta_2 A - K_6 I \\ f_7 &= \theta_3 Q + \tau_2 I - K_7 H \\ f_8 &= \alpha_1 A + \alpha_2 I + \alpha_3 H - \mu R \\ f_9 &= l_1 A + l_2 I + l_3 H - \phi D \\ f_{10} &= \Pi I + \Pi \theta H - \varepsilon W \end{aligned} \right\} \quad (8)$$

Then the following are obtained

$$\left| \frac{\partial f_1}{\partial S} \right| = |-\Omega - K_1| \leq \infty, \quad \left| \frac{\partial f_1}{\partial V} \right| = |-v_2| \leq \infty, \quad \left| \frac{\partial f_1}{\partial A} \right| = \left| -\frac{\beta \eta_1 S}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_1}{\partial H} \right| = \left| -\frac{\beta \eta_2 S}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_1}{\partial W} \right| = \left| -\frac{\beta \eta_3 S}{\chi_1 D + 1} \right| \leq \infty,$$

$$\left| \frac{\partial f_1}{\partial I} \right| = \left| -\frac{\beta S}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_1}{\partial E} \right| = \left| \frac{\partial f_1}{\partial Q} \right| = \left| \frac{\partial f_1}{\partial R} \right| = \left| \frac{\partial f_1}{\partial D} \right| = 0 \leq \infty,$$

$$\left| \frac{\partial f_2}{\partial S} \right| = |v_1| \leq \infty, \quad \left| \frac{\partial f_2}{\partial V} \right| = |-e\Omega - K_2| \leq \infty, \quad \left| \frac{\partial f_2}{\partial A} \right| = \left| -\frac{\beta \eta_1 eV}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_2}{\partial H} \right| = \left| -\frac{\beta \eta_2 eV}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_2}{\partial W} \right| = \left| -\frac{\beta \eta_3 eV}{\chi_1 D + 1} \right| \leq \infty,$$

$$\leq \infty, \quad \left| \frac{\partial f_2}{\partial I} \right| = \left| -\frac{\beta eV}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_2}{\partial E} \right| = \left| \frac{\partial f_2}{\partial Q} \right| = \left| \frac{\partial f_2}{\partial R} \right| = \left| \frac{\partial f_2}{\partial D} \right| = 0 \leq \infty,$$

$$\left| \frac{\partial f_3}{\partial S} \right| = |\Omega| \leq \infty, \quad \left| \frac{\partial f_3}{\partial V} \right| = |e\Omega| \leq \infty, \quad \left| \frac{\partial f_3}{\partial A} \right| = \left| \frac{\beta \eta_1 (S + eV)}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_3}{\partial H} \right| = \left| \frac{\beta \eta_2 (S + eV)}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_3}{\partial W} \right| = \left| \frac{\beta \eta_3 (S + eV)}{\chi_1 D + 1} \right| \leq \infty,$$

$$\leq \infty, \quad \left| \frac{\partial f_3}{\partial I} \right| = \left| -\frac{\beta (S + eV)}{\chi_1 D + 1} \right| \leq \infty, \quad \left| \frac{\partial f_3}{\partial E} \right| = |-K_3| \leq \infty, \quad \left| \frac{\partial f_3}{\partial Q} \right| = \left| \frac{\partial f_3}{\partial R} \right| = \left| \frac{\partial f_3}{\partial D} \right| = 0 \leq \infty,$$

$$\left| \frac{\partial f_4}{\partial S} \right| = \left| \frac{\partial f_4}{\partial V} \right| = \left| \frac{\partial f_4}{\partial A} \right| = \left| \frac{\partial f_4}{\partial I} \right| = \left| \frac{\partial f_4}{\partial H} \right| = \left| \frac{\partial f_4}{\partial R} \right| = \left| \frac{\partial f_4}{\partial D} \right| = \left| \frac{\partial f_4}{\partial W} \right| = 0 \leq \infty, \quad \left| \frac{\partial f_4}{\partial E} \right| = |\tau_1| \leq \infty, \quad \left| \frac{\partial f_4}{\partial Q} \right| = |-K_4| \leq \infty,$$

$$\left| \frac{\partial f_5}{\partial S} \right| = \left| \frac{\partial f_5}{\partial V} \right| = \left| \frac{\partial f_5}{\partial Q} \right| = \left| \frac{\partial f_5}{\partial I} \right| = \left| \frac{\partial f_5}{\partial H} \right| = \left| \frac{\partial f_5}{\partial R} \right| = \left| \frac{\partial f_5}{\partial D} \right| = \left| \frac{\partial f_5}{\partial W} \right| = 0 \leq \infty, \quad \left| \frac{\partial f_5}{\partial E} \right| = |\theta_1| \leq \infty, \quad \left| \frac{\partial f_5}{\partial A} \right| = |-K_5| \leq \infty,$$

$$\left| \frac{\partial f_6}{\partial S} \right| = \left| \frac{\partial f_6}{\partial V} \right| = \left| \frac{\partial f_6}{\partial E} \right| = \left| \frac{\partial f_6}{\partial Q} \right| = \left| \frac{\partial f_6}{\partial H} \right| = \left| \frac{\partial f_6}{\partial R} \right| = \left| \frac{\partial f_6}{\partial D} \right| = \left| \frac{\partial f_6}{\partial W} \right| = 0 \leq \infty, \quad \left| \frac{\partial f_6}{\partial A} \right| = |\theta_2| \leq \infty, \quad \left| \frac{\partial f_6}{\partial I} \right| = |-K_6| \leq \infty,$$

$$\left| \frac{\partial f_7}{\partial S} \right| = \left| \frac{\partial f_7}{\partial V} \right| = \left| \frac{\partial f_7}{\partial E} \right| = \left| \frac{\partial f_7}{\partial A} \right| = \left| \frac{\partial f_7}{\partial R} \right| = \left| \frac{\partial f_7}{\partial D} \right| = \left| \frac{\partial f_7}{\partial W} \right| = 0 \leq \infty, \quad \left| \frac{\partial f_7}{\partial Q} \right| = |\theta_3| \leq \infty, \quad \left| \frac{\partial f_7}{\partial I} \right| = |\tau_2| \leq \infty, \quad \left| \frac{\partial f_7}{\partial H} \right| = |-K_7| \leq \infty,$$

$$\left| \frac{\partial f_8}{\partial S} \right| = \left| \frac{\partial f_8}{\partial V} \right| = \left| \frac{\partial f_8}{\partial E} \right| = \left| \frac{\partial f_8}{\partial Q} \right| = \left| \frac{\partial f_8}{\partial R} \right| = \left| \frac{\partial f_8}{\partial W} \right| = 0 \leq \infty, \quad \left| \frac{\partial f_8}{\partial A} \right| = |\alpha_1| \leq \infty, \quad \left| \frac{\partial f_8}{\partial I} \right| = |\alpha_2| \leq \infty, \quad \left| \frac{\partial f_8}{\partial H} \right| = |\alpha_3| \leq \infty, \quad \left| \frac{\partial f_8}{\partial R} \right| = |-\mu| \leq \infty,$$

$$\left| \frac{\partial f_9}{\partial S} \right| = \left| \frac{\partial f_9}{\partial V} \right| = \left| \frac{\partial f_9}{\partial E} \right| = \left| \frac{\partial f_9}{\partial Q} \right| = \left| \frac{\partial f_9}{\partial R} \right| = \left| \frac{\partial f_9}{\partial W} \right| = 0 \leq \infty, \quad \left| \frac{\partial f_9}{\partial A} \right| = |l_1| \leq \infty, \quad \left| \frac{\partial f_9}{\partial I} \right| = |l_2| \leq \infty, \quad \left| \frac{\partial f_9}{\partial H} \right| = |l_3| \leq \infty, \quad \left| \frac{\partial f_9}{\partial D} \right| = |-\phi| \leq \infty,$$

$$\left| \frac{\partial f_{10}}{\partial S} \right| = \left| \frac{\partial f_{10}}{\partial V} \right| = \left| \frac{\partial f_{10}}{\partial E} \right| = \left| \frac{\partial f_{10}}{\partial A} \right| = \left| \frac{\partial f_{10}}{\partial Q} \right| = \left| \frac{\partial f_{10}}{\partial D} \right| = \left| \frac{\partial f_{10}}{\partial R} \right| = 0 \leq \infty, \quad \left| \frac{\partial f_{10}}{\partial I} \right| = |\Pi| \leq \infty, \quad \left| \frac{\partial f_{10}}{\partial H} \right| = |\Pi\theta| \leq \infty, \quad \left| \frac{\partial f_{10}}{\partial W} \right| = |-\varepsilon| \leq \infty.$$

Since, all the partial derivatives are continuous and bounded, then by Derrick and Grossman's theorem in Derrick and Grossman (1987) and Rabiun and Akinyemi (2016), the unique solution of Model (1) is established.

Positivity Solution of the Covid-19 Model

Theorem 2.2: The solution set $\{S(t), V(t), E(t), Q(t), A(t), I(t), H(t), R(t), D(t), W(t)\}$ of Model (1) is non-negative $\forall t \geq 0$, provided the initial conditions are non-negative.

Proof: It is readily seen that the first equation of Model (1) satisfies

$$\frac{dS}{dt} \geq -(\Omega + K_1)S \quad (9)$$

Solve (9) using the separable variable techniques to obtain

$$S(t) \geq S(0)e^{-\left(\int_0^t \Omega(q) dq + K_1 t\right)} \geq 0 \quad \forall t \geq 0.$$

Similarly, the second equation of system (1) gives

$$\frac{dV}{dt} \geq -(e\Omega + K_2)V \quad (10)$$

The solution of (10) gives

$$V(t) \geq V(0)e^{-\left(\int_0^t e\Omega(q) dq + K_2 t\right)} \geq 0 \quad \forall t \geq 0.$$

Following a similar argument, the rest equations of system (1) yields

$$\left. \begin{aligned} E(t) &\geq E(0)e^{-K_3 t} \geq 0 \quad \forall t \geq 0, \\ Q(t) &\geq Q(0)e^{-K_4 t} \geq 0 \quad \forall t \geq 0, \\ A(t) &\geq A(0)e^{-K_5 t} \geq 0 \quad \forall t \geq 0, \\ I(t) &\geq I(0)e^{-K_6 t} \geq 0 \quad \forall t \geq 0, \\ H(t) &\geq H(0)e^{-K_7 t} \geq 0 \quad \forall t \geq 0, \\ R(t) &\geq R(0)e^{-\mu t} \geq 0 \quad \forall t \geq 0, \\ D(t) &\geq D(0)e^{-\phi t} \geq 0 \quad \forall t \geq 0, \\ W(t) &\geq W(0)e^{-\varepsilon t} \geq 0 \quad \forall t \geq 0. \end{aligned} \right\} \quad (11)$$

Hence, the state variables are non-negative since their initial conditions

$(S(0), V(0), E(0), Q(0), A(0), I(0), H(0), R(0), D(0), W(0))$ are not negative. Hence, we conclude the proof.

Boundedness of Solution

Theorem 3: The set $\theta = \left\{ (S, V, E, Q, A, I, H, R, D, W) \in \mathbb{R}_+^{10} : N \leq \frac{P}{\mu}; D \leq \frac{d_1 P}{\phi \mu}; W \leq \frac{P \Pi (1 + \theta)}{\mu \varepsilon} \right\}$ is positively invariant and attractive with respect to Model (1)

Proof: Since $N(t) = S(t) + V(t) + E(t) + Q(t) + I(t) + H(t) + R(t)$ then the rate of change of the total active population has been obtained by adding the first-eighth equations of the system (1) to get

$$\frac{dN}{dt} = P - \mu N - \delta_1 A - \delta_2 I - \delta_3 H \quad (12)$$

It is readily seen that (12) becomes

$$\frac{dN}{dt} \leq P - \mu N \quad (13)$$

Solve (13) by integrating factor to have

$$N(t) \leq \frac{P}{\mu} + \left(N(0) - \frac{P}{\mu} \right) e^{-\mu t} \quad \forall t \geq 0. \quad (14)$$

Therefore as $t \rightarrow \infty$, $0 \leq N(t) \leq \frac{P}{\mu}$.

It is readily seen that $A(t) \leq \frac{P}{\mu}$, $I(t) \leq \frac{P}{\mu}$, and $H(t) \leq \frac{P}{\mu}$, since $0 \leq N(t) \leq \frac{P}{\mu}$. Then. The ninth equation of the system (1)

$$\frac{dD}{dt} \leq \frac{d_1 P}{\mu} - \phi D \quad (15)$$

Where $d_1 = \delta_1 + \delta_2 + \delta_3 + 3\mu$

The solution of (15) yields

$$D(t) \leq \frac{d_1 P}{\phi \mu} + \left(D(0) - \frac{d_1 P}{\phi \mu} \right) e^{-\phi t} \quad \forall t \geq 0. \quad (16)$$

As $t \rightarrow \infty$, $0 \leq D(t) \leq \frac{d_1 P}{\phi \mu}$.

Similarly, the solution of the last equation of system (1) is obtained as

$$W(t) \leq \frac{P\Pi(1+\theta)}{\mu\varepsilon} + \left(W(0) - \frac{P\Pi(1+\theta)}{\mu\varepsilon}\right)e^{-\varepsilon t} \quad \forall t \geq 0. \quad (17)$$

Hence, as $t \rightarrow \infty$, $0 \leq W(t) \leq \frac{P\Pi(1+\theta)}{\mu\varepsilon}$. Therefore, θ is positively invariant since N , D and W are bounded.

Application of NSFD2

The continuous dynamical model (1) is converted to its discrete form based on the rules and steps outlined in Section 2. Thus (1) becomes

$$\frac{S_{n+1}-S_n}{Z_1} = \frac{-\beta(A_n\eta_1+H_n\eta_2+W_n\eta_3+I_n)S_{n+1}}{\chi_1 D_{n+1}} - K_1 S_{n+1} + V_n v_2 + P \quad (18)$$

$$\frac{V_{n+1}-V_n}{Z_2} = \frac{-\beta e(A_n\eta_1+H_n\eta_2+W_n\eta_3+I_n)V_{n+1}}{\chi_1 D_{n+1}} - K_2 V_{n+1} + S_{n+1} v_1 \quad (19)$$

$$\frac{E_{n+1}-E_n}{Z_3} = \frac{-\beta(S_{n+1}+eV_{n+1})(A_n\eta_1+H_n\eta_2+W_n\eta_3+I_n)}{\chi_1 D_{n+1}} - K_3 E_{n+1} \quad (20)$$

$$\frac{Q_{n+1}-Q_n}{Z_4} = \tau_1 E_{n+1} - K_4 Q_{n+1} \quad (21)$$

$$\frac{A_{n+1}-A_n}{Z_5} = \theta_1 E_{n+1} - K_5 A_{n+1} \quad (22)$$

$$\frac{I_{n+1}-I_n}{Z_6} = \theta_2 A_{n+1} - K_6 I_{n+1} \quad (23)$$

$$\frac{H_{n+1}-H_n}{Z_7} = \theta_3 Q_{n+1} + \tau_2 I_{n+1} - K_7 H_{n+1} \quad (24)$$

$$\frac{R_{n+1}-R_n}{Z_8} = \alpha_1 A_{n+1} + \alpha_2 I_{n+1} + \alpha_3 H_{n+1} - \mu R_{n+1} \quad (25)$$

$$\frac{D_{n+1}-D_n}{Z_9} = l_1 A_{n+1} + l_2 I_{n+1} + l_3 H_{n+1} - \phi D_{n+1} \quad (26)$$

$$\frac{W_{n+1}-W_n}{Z_{10}} = \Pi I_{n+1} + \Pi \theta H_{n+1} - \varepsilon W_{n+1} \quad (27)$$

Where,

$$Z_8 = \frac{e^{\mu h}-1}{\mu}, \quad Z_9 = \frac{e^{\phi h}-1}{\phi}, \quad Z_{10} = \frac{e^{\varepsilon h}-1}{\varepsilon}, \quad \text{and } Z_i = \frac{e^{K_i h}-1}{K_i} \quad \forall i = 1, \dots, 7. \quad (28)$$

Make S_{n+1} , V_{n+1} , E_{n+1} , Q_{n+1} , A_{n+1} , I_{n+1} , H_{n+1} , R_{n+1} , D_{n+1} , and W_{n+1} subject formula from (18)-(27) respectively to have

$$S_{n+1} = \frac{((V_n v_2 + P)Z_1 + S_n)(\chi_1 D_{n+1})}{(\Psi_n + (\chi_1 D_{n+1})Z_1 + \chi_1 D_{n+1})} \quad (29)$$

$$V_{n+1} = \frac{(S_{n+1} Z_2 v_2 + V_n)(\chi_1 D_{n+1})}{(e\Psi_n + K_2(\chi_1 D_{n+1})Z_2 + \chi_1 D_{n+1})} \quad (30)$$

$$E_{n+1} = \frac{\Psi_n(S_{n+1} + eV_{n+1})Z_3 + E_n(\chi_1 D_{n+1})}{(K_3 Z_3 + 1)(\chi_1 D_{n+1})} \quad (31)$$

$$Q_{n+1} = \frac{Q_n + E_{n+1} Z_4 \tau_1}{K_4 Z_4 + 1} \quad (32)$$

$$A_{n+1} = \frac{A_n + E_{n+1} Z_5 \theta_1}{K_5 Z_5 + 1} \quad (33)$$

$$I_{n+1} = \frac{I_n + A_{n+1} Z_6 \theta_2}{K_6 Z_6 + 1} \quad (34)$$

$$H_{n+1} = \frac{H_n + I_{n+1} Z_7 \tau_2 + Q_{n+1} Z_7 \theta_3}{K_7 Z_7 + 1} \quad (35)$$

$$R_{n+1} = \frac{R_n + A_{n+1} Z_8 \alpha_1 + I_{n+1} Z_8 \alpha_2 + H_{n+1} Z_8 \alpha_3}{\mu Z_8 + 1} \quad (36)$$

$$D_{n+1} = \frac{D_n + A_{n+1} Z_9 l_1 + I_{n+1} Z_9 l_2 + H_{n+1} Z_9 l_3}{\phi Z_9 + 1} \quad (37)$$

$$W_{n+1} = \frac{W_n + I_{n+1} Z_{10} \Pi + H_{n+1} Z_{10} \Pi \theta}{\varepsilon Z_{10} + 1} \quad (38)$$

Where

$$\Psi_n = \beta(A_n \eta_1 + H_n \eta_2 + W_n \eta_3 + I_n)$$

RESULTS AND DISCUSSION

We simulated the COVID-19 model (29)-(38) for $T = 150$ days while using the initial conditions mentioned above by setting the stepsize $h = 0.01$ for NSFD-II. To validate the reliability of NSFD-II, the result obtained by NSFD-II was compared with the Runge-Kutta-Fehlberg (RKF45) method built-in Maple 18 software.

The results generated by NSFD-II and RKF45 methods for the population of susceptible individuals are displayed in Figure 1. Both methods show a gradual decrease in the population of susceptible humans for about 10 days and become steady for the remaining simulation period.

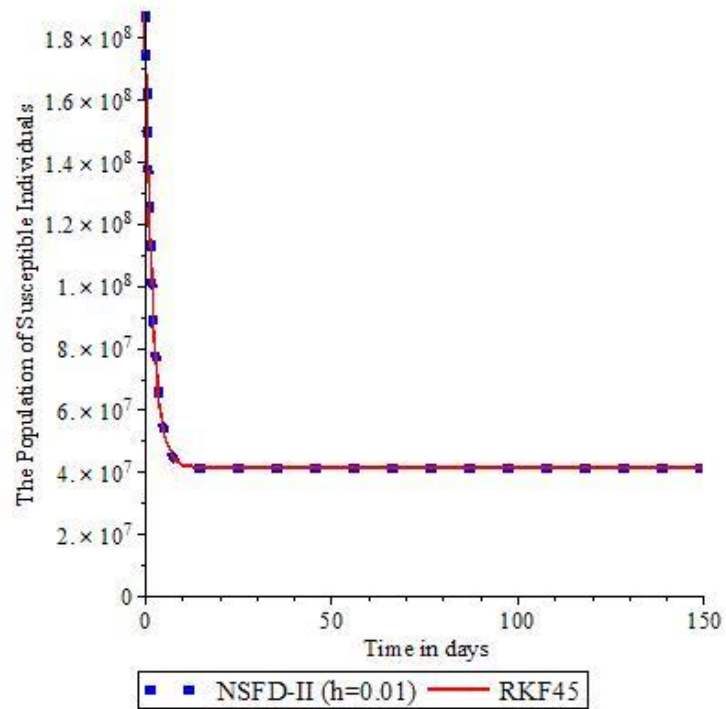


Figure 1: Graphical Comparison for $S(t)$

The population profile for the vaccinated humans obtained by NSF-D-II and RKF45 methods is shown in Figure 2. The population of vaccinated humans gradually increases first, before becoming steady. The figure also shows that both methods agree that the population

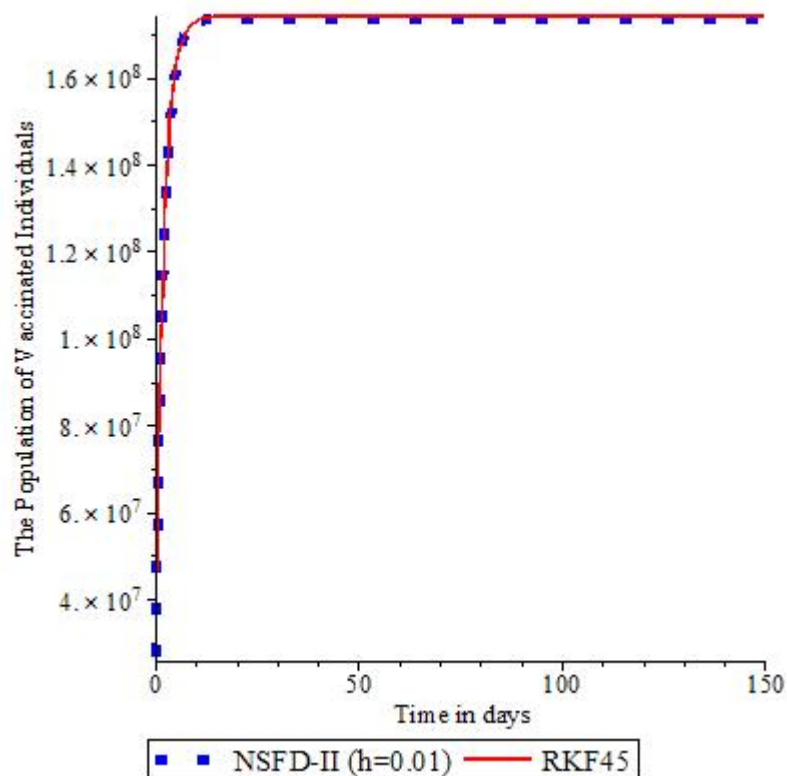


Figure 2: Graphical Comparison for $V(t)$

Figures 3-4 depict the population profile for the exposed and quarantined humans respectively. The figures show that both methods describe that the population of the exposed and quarantined decreases to zero.

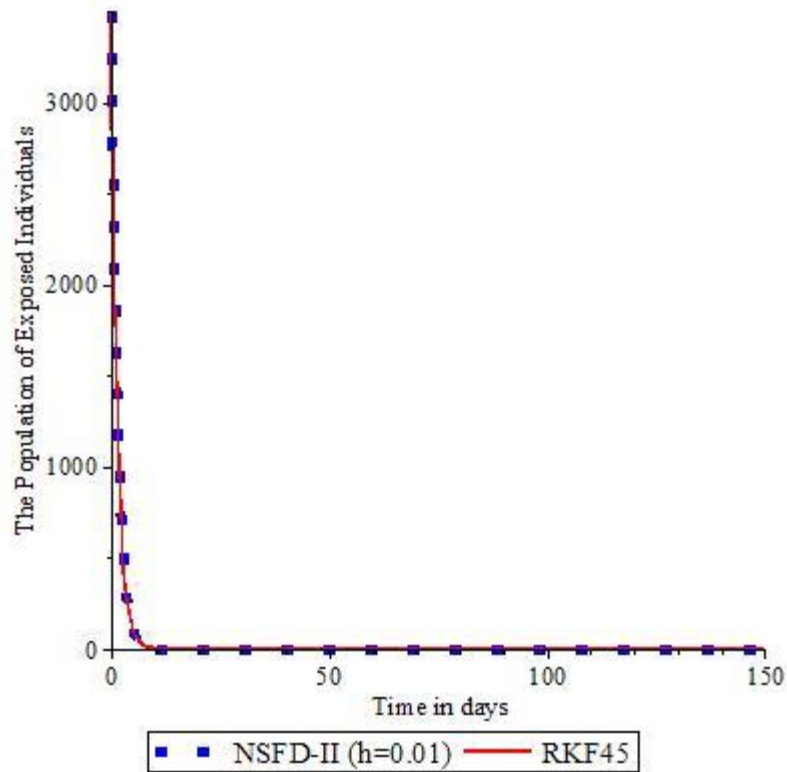


Figure 3: Graphical Comparison for $E(t)$

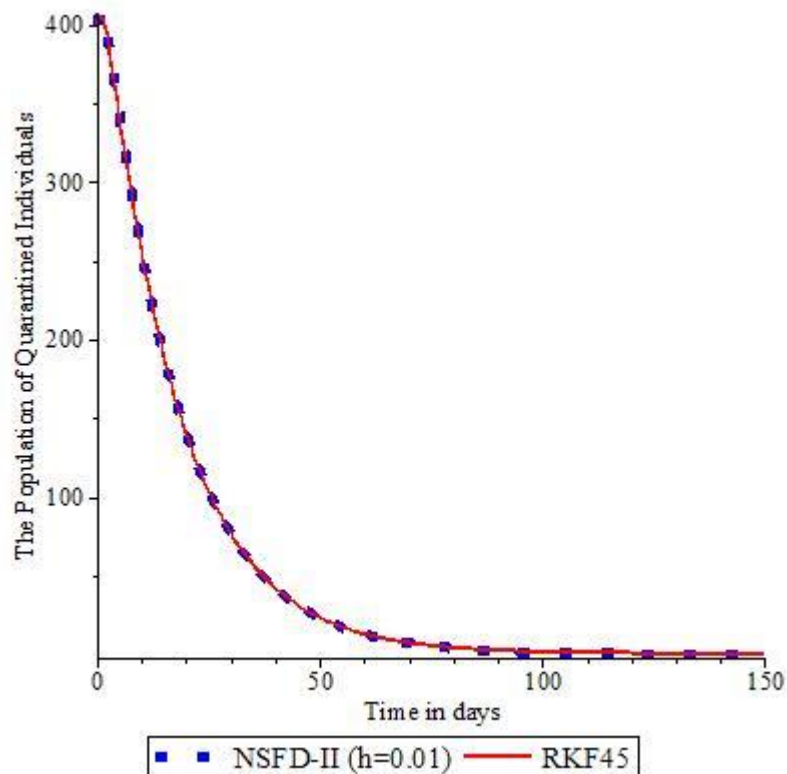


Figure 4: Graphical Comparison for $Q(t)$

Figures 5-6 present the population profile for the asymptomatic and symptomatic humans respectively. Both figures show that NSFD-II and RKF45 methods convey that the population of the individuals in the A and I compartments gradually increases first before declining to zero.

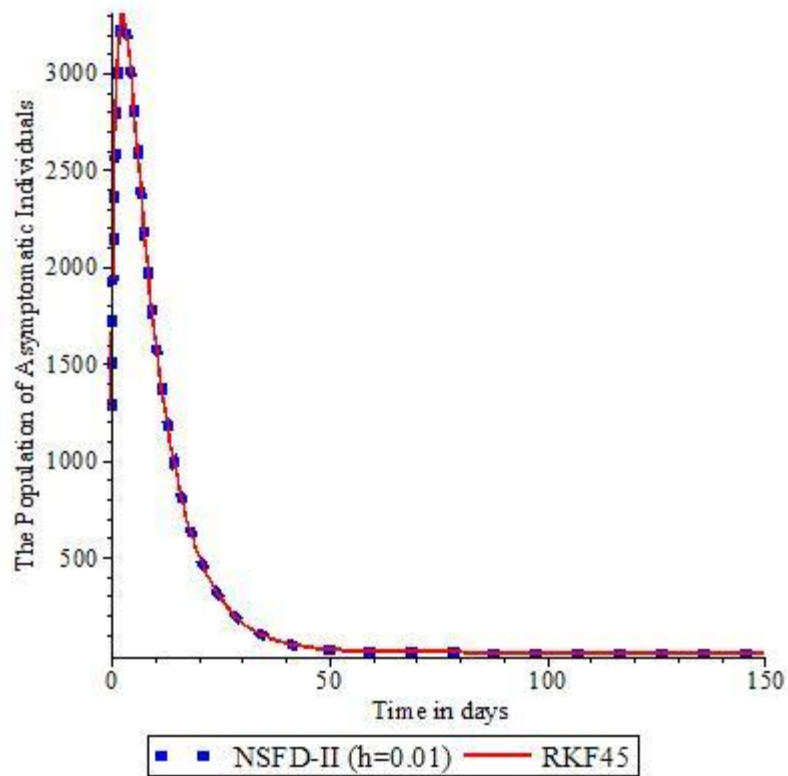


Figure 5: Graphical Comparison for $A(t)$

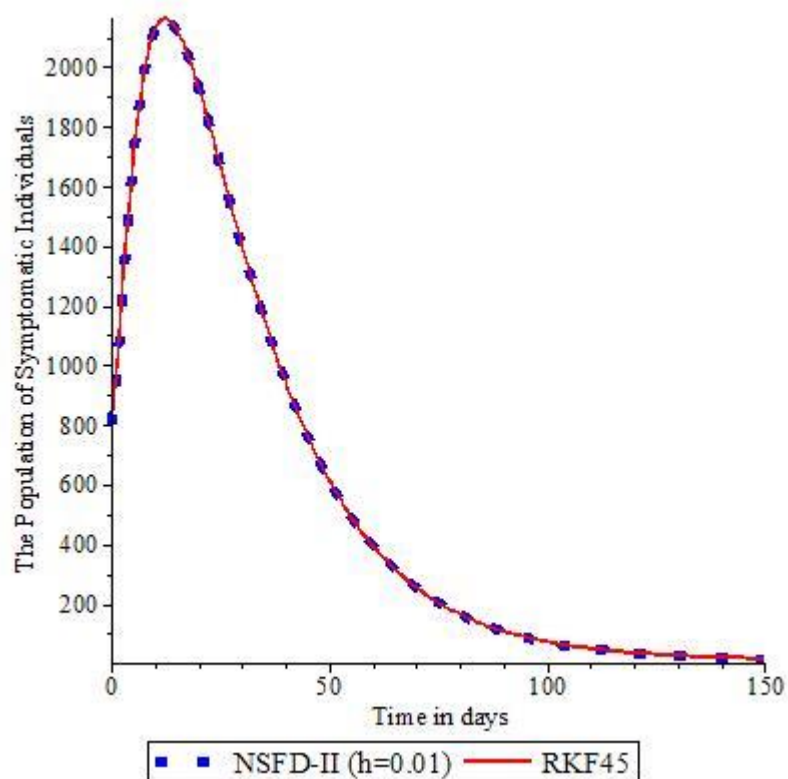


Figure 6: Graphical Comparison for $I(t)$

A graphical comparison between the results obtained by NSFD-II and RKF45 for the population of hospitalized humans is displayed in Figure 7. It is observed from Figure 7

that first there was a drop in the number of hospitalized humans, shortly followed by an increase before decreasing to zero.

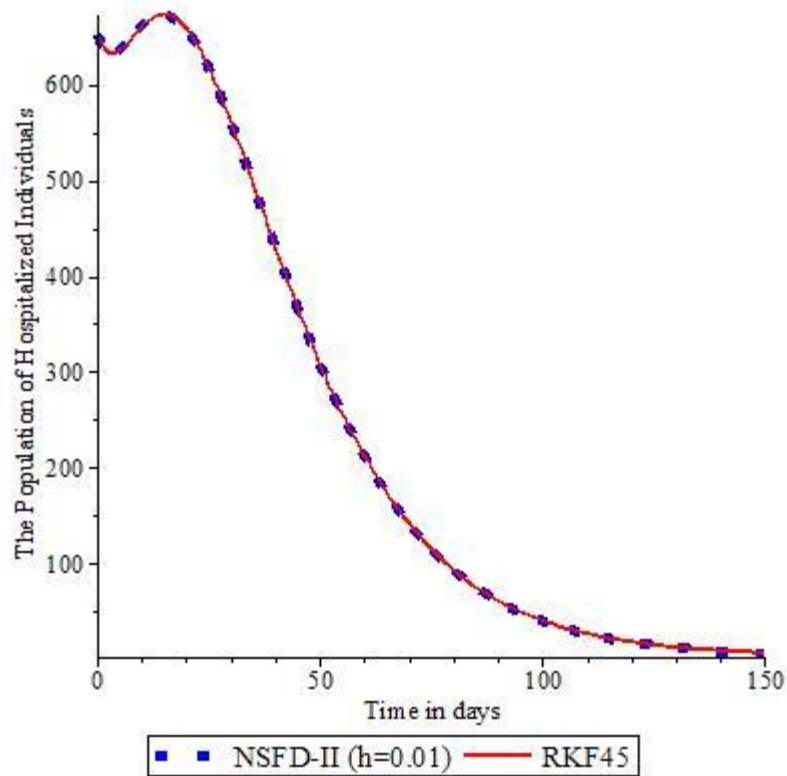


Figure 7: Graphical Comparison for $H(t)$

The population profile for the recovered individuals generated by NSFD-II and RKF45 is shown in Figure 8. The figure shows that the number of those who recovered from COVID-19 infection increases for about 60 days and later begins to decrease.

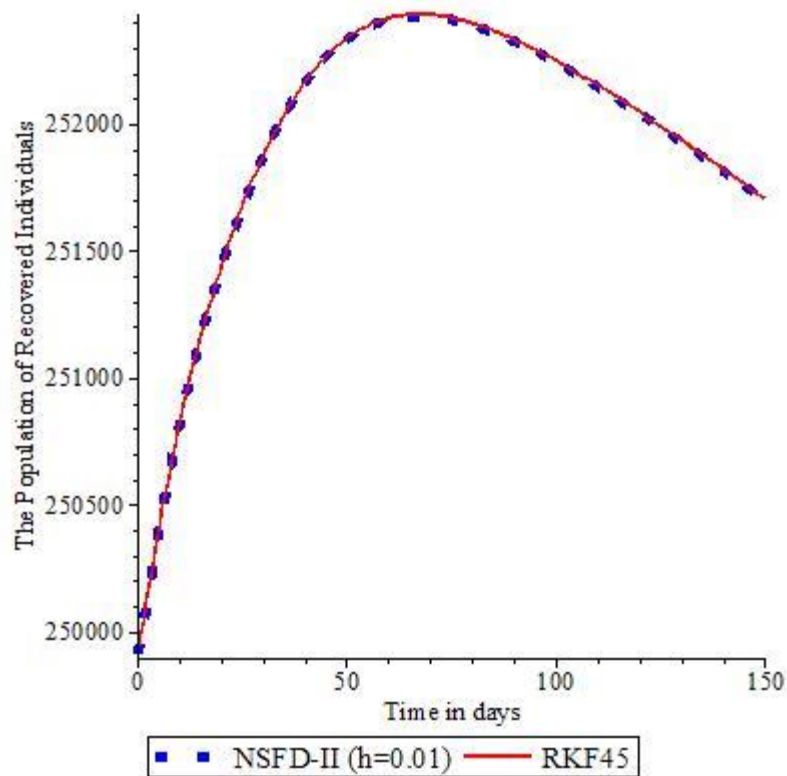
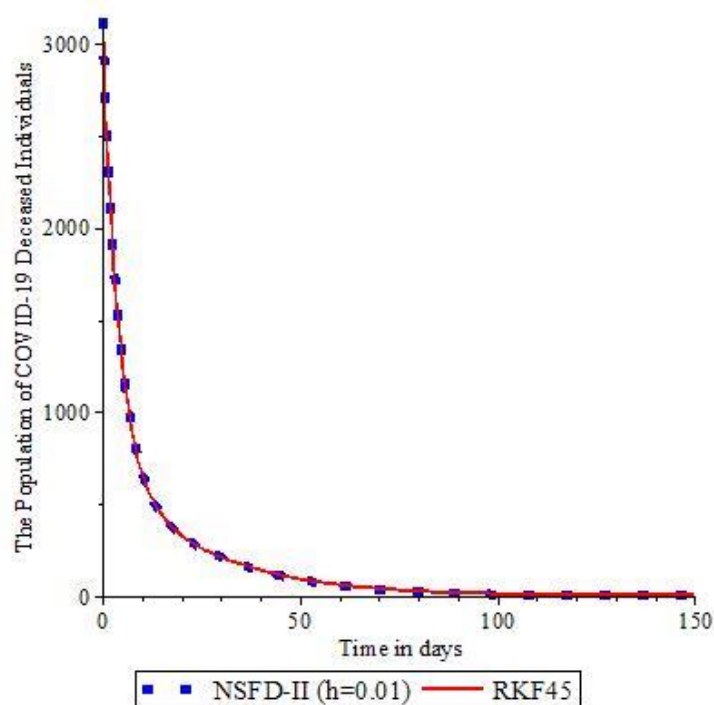
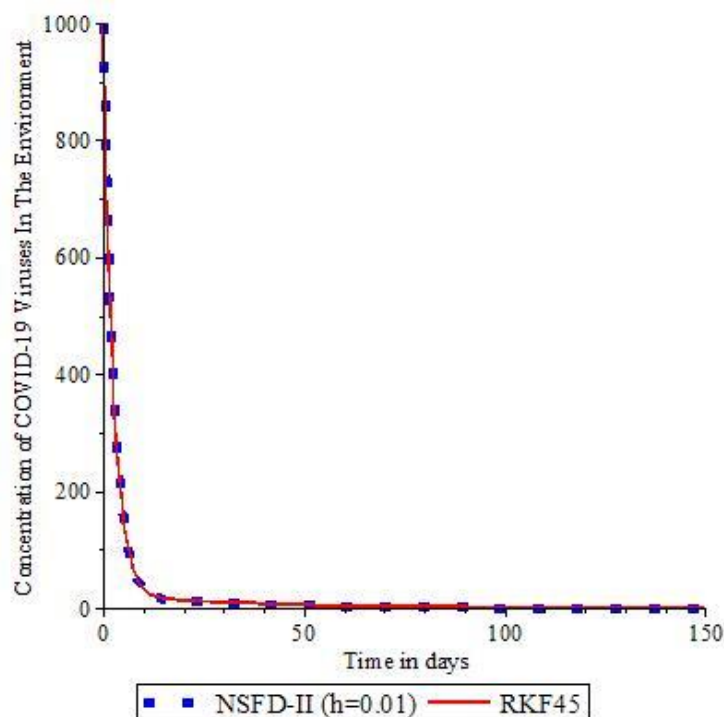


Figure 8: Graphical Comparison for $R(t)$

The population and concentration profiles for COVID-19 deceased individuals and COVID-19 viruses in the environment are depicted in Figures 9 -10 respectively. Figures 9 -10 show that $D(t)$ and $W(t)$ decreases to zero.

Figure 9: Graphical Comparison for $D(t)$ Figure 10: Graphical Comparison for $W(t)$

Finally, Figures 1-10 show that the result obtained by NSFD-II agrees excellently well with those of RKF45 despite that the default RKF45 built-in Maple 18 software makes use of adaptive step size to ensure that the absolute and relative errors for each iteration are not above $1e-7$ and $1e-6$. Thus, this makes RKF45 more cumbersome and difficult to implement when compared with NSFD-II.

CONCLUSION

An application of NSFD-II to solve a deterministic mathematical model for the transmission dynamics of

COVID-19 in the presence of fear of infection was considered in this study. This model was shown to possess a unique solution that is positive and bounded. The solution obtained by NSFD-II was compared graphically with those obtained by the default Runge-Kutta Fehlberg (RKF45) built-in Maple 18 software. The comparison shows that both methods are in excellent agreement even though the RKF45 is more cumbersome and not easy to implement when compared with NSFD-II. Thus, the use NSFD-II method is reliable and efficient and should be applied to solve other nonlinear real phenomena.

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